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# Log-based Evaluation of Label Splits for Process Models

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#### Abstract

Process mining techniques aim to extract insights in processes from event logs. One of the challenges in process mining is identifying interesting and meaningful event labels that contribute to a better understanding of the process. Our application area is mining data from smart homes for elderly, where the ultimate goal is to signal deviations from usual behavior and provide timely recommendations in order to extend the period of independent living. Extracting individual process models showing user behavior is an important instrument in achieving this goal. However, the interpretation of sensor data at an appropriate abstraction level is not straightforward. For example, a motion sensor in a bedroom can be triggered by tossing and turning in bed or by getting up. We try to derive the actual activity depending on the context (time, previous events, etc.). In this paper we introduce the notion of label refinements, which links more abstract event descriptions with their more refined counterparts. We present a statistical evaluation method to determine the usefulness of a label refinement for a given event log from a process perspective. Based on data from smart homes, we show how our statistical evaluation method for label refinements can be used in practice. Our method was able to select two label refinements out of a set of candidate label refinements that both had a positive effect on model precision.

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#### 1. Introduction

Process mining is a fast growing discipline that brings together knowledge and techniques from computational intelligence, data mining, process modeling and process analysis<sup>15</sup>. The process mining task is the automatic or semi-automatic analysis of events that are logged during process execution, where event records contain information on what was done, by whom, for whom, where, when, etc. Events are grouped into cases (process instances), e.g. per patient for a hospital log, or per insurance claim for an insurance company. An important task within process mining is *process discovery*, which focuses on extracting interpretable models of processes from event logs. One of the attributes of the events is usually used as its label. These event labels are then used as transition/activity labels in the process models created by process discovery algorithms.

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Fig. 1: A Petri net derived from the event log in Table 1

Table 1: The corresponding smart home sensor event log with refined labels

Process mining takes its roots in the field of business process management, where the definition of labels for events is considered to be rather straightforward. In recent years, the application domain of process mining has broadened. A wide variety of event types can be used as input and analysis may be challenging. One of the most challenging application areas is LifeLogging, which focuses on acquisition and analysis of personal daily life data. LifeLogs amongst others combine data collected through mobile phones, wearable devices, and/or smart home sensors. The emergence of LifeLogging tools and the resulting increase in availability of activity data enable a process-centric analysis of human behavior<sup>14</sup>. The aim of process mining analysis on LifeLogging data is to find frequent activity patterns and represent them in a human interpretable process model. Such a process model could then also be used to detect deviations from one's regular behavior. Process mining in the human behavior application domain closely

Id	Timestamp	Address	Sensor	Heart rate	Activity	
1 2 3 4 5 6 	03/11/2015 02:45 03/11/2015 03:23 03/11/2015 04:59 03/11/2015 06:04 03/11/2015 08:45 03/11/2015 09:10 03/11/2015	Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7	Bedroom motion Bedroom motion Bedroom motion Bedroom motion Living room motion	74 72 71 73 85 79	Tossing & turning Tossing & turning Tossing & turning Tossing & turning Getting up Living room motion	
7 8 9 10 11	03/12/2015 01:01 03/12/2015 03:13 03/12/2015 07:24 03/12/2015 08:34 03/12/2015 09:12 03/12/2015	Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7	Bedroom motion Bedroom motion Bedroom motion Bedroom motion Living room motion	73 75 74 79 76	Tossing & turning Tossing & turning Tossing & turning Getting up Living room motion	
12 13 14 15 16 17 18	03/13/2015 00:45 03/13/2015 02:29 03/13/2015 05:19 03/13/2015 05:34 03/13/2015 05:39 03/13/2015 08:37 03/13/2015 08:52 03/13/2015	Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7	Bedroom motion Bedroom motion Bedroom motion Bedroom motion Bedroom motion Living room motion 	75 75 74 79 77 79 78	Tossing & turning Tossing & turning Tossing & turning Tossing & turning Tossing & turning Getting up Living room motion	
19 20 21 22	03/14/2015 03:41 03/14/2015 05:00 03/14/2015 08:52 03/14/2015 09:30 03/14/2015	Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7	Bedroom motion Bedroom motion Bedroom motion Living room motion	75 74 75 74	Tossing & turning Tossing & turning Getting up Living room motion	
23 24 25 26	03/15/2015 02:11 03/15/2015 02:34 03/15/2015 08:35 03/15/2015 08:57 03/15/2015	Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7 Mountain Rd. 7	Bedroom motion Bedroom motion Bedroom motion Living room motion	77 76 79 77	Tossing & turning Tossing & turning Getting up Living room motion	

relates to the field of activity recognition, which aims to detect human activities from sensors and finding patterns between human activities<sup>2</sup>. Process mining, however, aims to produce interpretable models that can provide insights by visually inspecting them. In contrast, most activity recognition techniques produce non-interpretable models.

Imagine an elderly person of whom we want to discover a process model describing his/her daily behavior. Events are generated by sensors, either periodically (e.g. by a temperature sensor or heart rate monitor), or triggered by some activity (e.g. motion). Table 1 shows an example log obtained by fusing data from such sensors. The dots indicate that only a fraction of the logged events are shown. Assigning meaningful labels to these events is not straightforward. A *Bedroom motion* event can be caused by different human activities, e.g. by *Tossing & turning* or by *Getting up*. In some cases it is necessary to distinguish between *Tossing & turning* and *Getting up*, for example when we aim to generate a timely reminder to take medication that needs to be taken before breakfast. Based on contextual information (e.g. a specific increase in heart rate, a time stamp, etc.), the distinction between the two types of activities might be identified, and each event with label *Bedroom motion* can be refined into either *Tossing & turning* or *Getting up*. The last column in Table 1 shows the desired event labels. Figure 1 shows a process model that can be deduced from such a log using existing process discovery techniques, like the ones from  $1^{7,21}$ .

Many relabelings of *Bedroom motion* events are possible. Expert knowledge, data mining or machine learning techniques can be used to generate ideas for potential labeling functions. The goal of this labeling function is to give "similar" events the same label. However, similarity is a relative notion, *so the initially chosen labeling function can be too abstract or too fine-grained to generate an informative process model*. Once a process discovery algorithm has been applied and a process model is obtained, one can assess whether the labeling function used on the original event log allowed the process discovery algorithm to discover an informative process model. However, it is computationally costly to apply process mining algorithms to multiple event logs generated from a single original event log using different event labeling functions with varying levels of abstraction. Therefore, we provide a statistical approach to evaluate label refinement usefulness in the context of process discovery that is based on significance testing of differences in event ordering relations. The Fodina<sup>20</sup> and the  $\alpha^{*7}$  process discovery algorithms assume that there is one column in the event log that indicates the activity and refine this label based on a threshold of differentness on the event labels occurring directly before and after. In this paper we assume that the information what activity is performed is spread over multiple columns. We choose one column as primary activity column and refine the activity labels based on the other columns and temporal information. We validate whether a refinement makes sense from a process perspective by taking into account all temporal event information in the event log, using statistical testing and information gain. Evaluating splits based on information gain is a well-known approach in the area of decision tree learning<sup>11</sup>, where ground truth labels are available in contrast to the label refinement setting. Label refinements draw similarities with automatic learning of ontologies<sup>8</sup> in the sense that both are concerned with inferring multiple levels of semantic interpretations from data. Ontology quality evaluation techniques<sup>1</sup> can be used to evaluate (automatically inferred) ontologies, however these techniques are not processcentric, i.e., they do not take into account ordering relations between elements of the ontology in execution sequences.

Section 2 gives formal definitions of label refinements, process models, and related concepts. In Section 3, we discuss when a label refinement is useful from a process mining perspective. A statistical method to evaluate the usefulness of a label refinement is described in Section 4. In Section 5 we discuss the results of the proposed method on a real life smart home data set. We draw conclusions in Section 6.

#### 2. Label Refinements & Process Models

In this section we introduce the notions related to event logs and relabeling functions for traces and then define the notions of refinements and abstractions. We also introduce the Petri net process model notation.

We use the usual sequence definition, and denote a sequence by listing its elements, e.g. we write  $\langle a_1, a_2, ..., a_n \rangle$  for a (finite) sequence  $s : \{1, ..., n\} \rightarrow A$  of elements from some alphabet A, where  $s(i) = a_i$  for any  $i \in \{1, ..., n\}$ . The length of a sequence  $s : \{1, ..., n\} \rightarrow A$  is |s| = n;  $s_1 s_2$  denotes the concatenation of sequences  $s_1$  and  $s_2$ . A *language*  $\mathfrak{L}$  over an alphabet A is a set of sequences over A.  $\mathfrak{L}^p$  is the prefix closure of a language  $\mathfrak{L}$  (with  $\mathfrak{L} \subseteq \mathfrak{L}^p$ ).

An event is the most elementary element of an event log. Let I be a set of event identifiers,  $\mathcal{T}$  be a set of timestamps, and  $\mathcal{A}_1 \times \cdots \times \mathcal{A}_n$  be an attribute domain consisting of n attributes (e.g. resource, activity name, cost, etc.), each of a certain type. An event is a tuple  $e = (i, t, a_1, \dots, a_n)$ , with  $i \in I$ ,  $t \in \mathcal{T}$ , and  $(a_1, \dots, a_n) \in \mathcal{A}_1 \times \cdots \times \mathcal{A}_n$ . The *event label* of an event is the attribute set  $(a_1 \dots, a_n)$ ;  $e_i$ ,  $e_t$  and  $e_a$  respectively denote the identifier, the timestamp and label of event e.  $\mathcal{E} = I \times \mathcal{T} \times \mathcal{A}_1 \times \cdots \times \mathcal{A}_n$  is a universe of events over  $\mathcal{A}_1, \dots, \mathcal{A}_n$ . The lines of Table 1, where we do not consider the *activity* column for now, are events from an event universe over the event attributes *sensor*, *address*, and *heart rate*.

Events are often considered in the context of other events. We call  $E \subseteq \mathcal{E}$  an *event set*, if *E* does not contain any events with the same event identifier. The events in Table 1 together form an event set. A *trace*  $\sigma$  is a finite sequence formed by the events from an event set  $E \subseteq \mathcal{E}$  that respects the time ordering of events, i.e. for all  $k, m \in \mathbb{N}$ ,  $1 \le k < m \le |E|$ , we have:  $\sigma(k)_t \le \sigma(m)_t$ . We define the *universe of traces* over event universe  $\mathcal{E}$ , denoted  $\Sigma(\mathcal{E})$ , as the set of all possible traces over  $\mathcal{E}$ . We omit  $\mathcal{E}$  in  $\Sigma(\mathcal{E})$  and use the shorter notation  $\Sigma$  when the event universe is clear from the context.

Often it is useful to partition an event set into smaller sets in which events belong together according to some criterion. We might for example be interested in discovering the typical behavior of households over the course of a day. In order to do so, we can e.g. group together events with the same *address* and the same day-part of the *timestamp*, as indicated by the horizontal lines in Table 1. For each of these event sets, we can construct a trace; time stamps define the ordering of events within the trace. For events of a trace having the same time stamps, an arbitrary ordering can be chosen within a trace.

An event partitioning function is a function  $ep : \mathcal{E} \to T_{id}$  that defines the partitioning of an arbitrary set of events  $E \subseteq \mathcal{E}$  from a given event universe  $\mathcal{E}$  into event sets  $E_1, \ldots, E_j, \ldots$  where each  $E_j$  is the maximal subset of E such that for any  $e_1, e_2 \in E_j$ ,  $ep(e_1) = ep(e_2)$ ; the value of ep shared by all the elements of  $E_j$  defines the value of the *trace attribute*  $T_{id}$ . Note that complex, multidimensional trace attributes are also possible, i.e. a combination of the name of the person performing the event activity and the date of the event, so that every trace contains activities of one person during one day. The event sets obtained by applying an event partitioning can be transformed into traces (respecting the time ordering of events).

An event log *L* is a finite set of traces  $L \subseteq \Sigma(\mathcal{E})$ .  $A_L \subseteq \mathcal{A}_1 \times \cdots \times \mathcal{A}_n$  denotes the *alphabet of event labels* that occur in log *L*. The traces of a log are often transformed before doing further analysis: very detailed but not necessarily informative event descriptions are transformed into some *informative* and *repeatable* labels. For the labels of the log in

Table 1, the heart rate values can be abstracted to *low, normal*, and *high* or the label can be redefined to a subset of the event attributes. Next to that, if the event partitioning function maps each event from Table 1 to its address and the day-part of the timestamp, these attributes (indicated in gray) become the trace attribute and can safely be removed from individual events. The new label is then defined as a combination of the sensor and abstracted heart rate values.

After this relabeling step, some traces of the log can become identically labeled (the event id's would still be different). The information about the number of occurrences of a sequence of labels in an event log is highly relevant for process mining, since it allows differentiating between the main stream behavior of a process (frequently occurring behavioral patterns) and exceptional behavior.

Let  $\Sigma(\mathcal{E})$  and  $\Sigma'(\mathcal{E}')$  be two universes of traces defined over event universes  $\mathcal{E}, \mathcal{E}'$ . A function  $l : \Sigma \to \Sigma'$  is a *trace* relabeling function if for all traces  $\sigma, \gamma \in \Sigma$  such that if  $\sigma$  is a prefix of  $\gamma$ ,  $l(\sigma)$  is a prefix of or equal to  $l(\gamma)$ . We lift *l* to event logs: for  $L \subseteq \Sigma$ , the relabeling l(L) is defined as  $\{l(\sigma) | \sigma \in L\}$ .

Often, relabeling functions are defined using a more narrow approach: first defining an event relabeling function and then lifting that function to traces. In the context of business processes, event relabeling functions are mostly mere projections of events on the values of a single attribute, such as *activity name*. We consider a more general definition to allow for history-dependent interpretation of events, which is necessary in the context of LifeLogging. Prefix preservation requirement is necessary to allow for logging, compliance checking and other forms of analysis performed at run time.

Let  $\Sigma$ ,  $\Sigma_1$ , and  $\Sigma_2$  be trace universes over  $\mathcal{E}, \mathcal{E}_1, \mathcal{E}_2$  respectively with  $\mathcal{E}, \mathcal{E}_1, \mathcal{E}_2$  being pairwise different. Let  $l_1 : \Sigma \to \Sigma_1$  and  $l_2 : \Sigma \to \Sigma_2$  be trace relabeling functions. Relabeling function  $l_1$  is a *refinement* of relabeling function  $l_2$ , denoted by  $l_1 \leq l_2$ , iff  $\forall_{\sigma_1, \sigma_2 \in \Sigma} : l_1(\sigma_1) = l_1(\sigma_2) \implies l_2(\sigma_1) = l_2(\sigma_2); l_2$  is then called an *abstraction* of  $l_1$ . We call a refinement  $l_1$  of  $l_2$  a *strict* refinement, denoted by  $l_1 < l_2$ , when  $\exists_{\sigma_1, \sigma_2 \in \Sigma} : l_1(\sigma_1) = l_2(\sigma_2)$ . We call refinement  $l_1$  of  $l_2$  an *equal length* refinement, denoted by  $l_1 \leq l_2$ , when  $\forall \sigma \in \Sigma : |l_1(\sigma)| = |l_2(\sigma)|$ .

Let  $\Sigma, \Sigma_1$  be trace universes over  $\mathcal{E}, \mathcal{E}_1$  respectively,  $l : \Sigma \to \Sigma_1$  a trace relabeling function, and  $\mathfrak{L}_1$  be a language  $\mathfrak{L}_1 \subseteq \Sigma_1$  over  $\mathcal{E}_1$ . Trace concretization  $l^{-1} : \Sigma_1 \to 2^{\Sigma}$  is a function defined as  $l^{-1}(\sigma_1) = \{\sigma \in \Sigma | l(\sigma) = \sigma_1\}$ , for each  $\sigma_1 \in \Sigma_1$ . Language concretization of  $\mathfrak{L}_1$  is language  $l^{-1}(\mathfrak{L}_1) = \bigcup_{\sigma_1 \in \mathfrak{L}_1} l^{-1}(\sigma')$ .

The goal of process discovery is to discover a process model that represents the behavior seen in an event log. A frequently used process modeling notation in the process mining field is the Petri net<sup>12</sup>. Petri nets are directed bipartite graphs consisting of transitions and places, connected by arcs. Transitions represent activities, while places represent the enabling conditions of transitions. Labels are assigned to transitions to indicate the type of activity that they model. A special label  $\tau$  is used to represent invisible transitions, which are only used for routing purposes and not recorded in the execution log.

A labeled Petri net  $N = \langle P, T, F, A_M, \ell \rangle$  is a tuple where P is a finite set of places, T is a finite set of transitions such that  $P \cap T = \emptyset$ ,  $F \subseteq (P \times T) \cup (T \times P)$  is a set of directed arcs, called the flow relation,  $A_M$  is an alphabet of labels representing activities, with  $\tau \notin A_M$  being a label representing invisible events, and  $\ell : T \to A_M \cup \{\tau\}$  is a labeling function that assigns a label to each transition. For a node  $n \in (P \cup T)$  we use  $\bullet n$  and  $n \bullet$  to denote the set of input and output nodes of n, defined as  $\bullet n = \{n'|(n', n) \in F\}$  and  $n \bullet = \{n|(n, n') \in F\}$ . An example of a Petri net can be seen in Figure 1, where circles represent places and squares represent transitions.

A state of a Petri net is defined by its marking  $M \in \mathbb{N}^P$  being a multiset of places. A marking is graphically denoted by putting M(p) tokens on each place  $p \in P$ . A pair (N, M) is called a marked Petri net. State changes occur through transition firings. A transition t is enabled (can fire) in a given marking M if each input place  $p \in {}^{\bullet}t$  contains at least one token. Once a transition fires, one token is removed from each input place of t and one token is added to each output place of t, leading to a new marking M' defined as  $M' = M - {}^{\bullet}t + t {}^{\bullet}$ . A firing of a transition t leading from marking M to marking M' is denoted as  $M \xrightarrow{\ell(t)} M'$ .  $M_1 \xrightarrow{\ell(\sigma)} M_2$  indicates that  $M_2$  can be reached from  $M_1$  through a firing sequence  $\sigma' \in A_M^*$ . Many process modeling notations have formal executional semantics and define a language of accepting traces  $\mathfrak{L}$ . For Petri net  $N_2$  in Figure 2,  $\mathfrak{L}(N_2) =$ {(Bedroom motion, Livingroom Motion), (Bedroom motion, Bedroom motion, Livingroom Motion), (Bedroom motion,  $\ldots$ , Bedroom motion, Livingroom Motion)}.

#### 3. On the Quality of Label Refinements for Process Mining

Process discovery algorithms discover a process model based on an event log, where event labels are obtained by applying an event relabeling function to an original log. The main quality metrics discovered process models are fitness,



Fig. 2: Petri nets discovered from two event logs obtained from the same event set with different relabeling functions.

precision, generalization and simplicity<sup>15</sup>. *Fitness* represents the share of the behavior seen in the log that is allowed by the process model. *Precision* aims at narrowing the set of traces that belong to the language of the discovered process model, but was not observed in the event log. *Generalization* aims at preventing overfitting, and *simplicity* measures the "understandability" and "well-structuredness" of models.

Intuitively, an event relabeling function is better than another one if it improves the quality of the discovered model along these quality dimensions. However, the quality metrics are currently defined in such a way that only results of discovery algorithms applied to the very same log can be compared, while two different relabeling functions produce logs with different event labels. The Petri net  $N_1$ in Figure 2 has perfect precision and fitness for the event log with labels as shown in the refined label column of Table 1. At the same time, Petri net  $N_2$  has perfect fitness and precision for the event log with labels as in the sensor column of Table 1. However, Petri net  $N_1$  is useful for the purpose of sending a reminder message to take medicines after getting up, while Petri net  $N_2$  is not. This suggests that Petri net  $N_1$  is more precise than  $N_2$ , but only with respect to



Fig. 3: Comparing two event relabeling functions

the original log. Thus we have to make the comparison in the context of the original log. Suppose we have a set of events E, which is part of some universe of events  $\mathcal{E}$ . We choose a case identifier and build an event log L from E. Then we choose relabeling functions  $l_1$  and  $l_2$  with  $l_1 < l_2$  and obtain  $L_1 = l_1(L)$  and  $L_2 = l_2(L)$  (see Figure 3). Applying process discovery to  $L_1$  and  $L_2$  results in two process models, which respectively accept languages  $\mathfrak{L}_1$  and  $\mathfrak{L}_2$ . These languages cannot be compared directly, since they contain traces consisting of different event labels. Precision metrics look at "redundant" traces in the mined models with respect to the log used as input for the discovery algorithm (see e.g.<sup>10,13</sup>). Using the inverse functions  $l_1^{-1}$ ,  $l_2^{-1}$ , every trace of  $\mathfrak{L}_1$  and  $\mathfrak{L}_2$  can be mapped to a set of traces built from the events from  $\mathcal{E}$ . Taking the union of the sets obtained with  $l_1^{-1}$ ,  $l_2^{-1}$  over the traces of the languages, we obtain comparable languages and can conclude whether the relabeling function results in a model that is more precise with respect to the original log.

Fitness and simplicity of the models depend mostly on the performance of the process discovery algorithm, and not on the choice of the relabeling function. Precision defined in terms of events of the original universe  $\mathcal{E}$  of events is however highly dependent on the appropriateness of the relabeling function: choosing a more refined relabeling function can increase the precision by eliminating the behavior that would be allowed in the model discovered with a more abstract relabeling function. Generalization can potentially suffer as the result of a higher precision.

#### 3.1. Label Refinement Quality

The comparison of the languages generated by models is not feasible due to its complexity; for many classes of process models, including Petri nets, the problem of language inclusion is just not decidable. Therefore, we need a different, practical approach to deciding on the usefulness of a relabeling function refinement. We start with discussing the usefulness by comparing the discovered models.

Consider event log L, relabeling functions  $l_1, l_2, l_3$  such that  $l_2 < l_1 \land l_3 < l_1$ , and event logs  $L_1 = l_1(L), L_2 = l_2(L), L_3 = l_3(L)$ . Let the  $N_1, N_2, N_3$  in Figure 4 be the Petri nets obtained by applying process discovery to  $L_1, L_2, L_3$  respectively. The square inside the transition between places  $p_3$  and  $p_4$  indicates that it is a subprocess.

We can see that refinement  $l_2$  does not lead to a meaningful interpretation of b as  $b_1$  and  $b_2$ , since the behavior of the model is not related to the choice between  $b_1$  and  $b_2$ : transitions labeled with  $b_1$  and  $b_2$  have the same input and output places. Refinement  $l_2$  does not provide new insight and unnecessarily harms the understandability of the Petri net by cre-



Fig. 4:  $N_2$  is a non-useful refinement and  $N_3$  is a useful refinement of  $N_1$ .

Table 2: Log-based ordering relations and their use by process discovery algorithms

Table 3: A Log statistic in contingency table form

Ordering relation	Miners using the relation		$ $ $a_1$	<i>a</i> <sub>2</sub> <i>a</i>
Direct successor Length-two loop Direct/indirect successor	<i>a</i> miner <sup>17</sup> , $a^{++}$ miner <sup>22</sup> , Multi-phase miner <sup>18</sup> , Heuristics miner <sup>21</sup> $a^{++}$ miner <sup>22</sup> , Multi-phase miner <sup>18</sup> , Heuristics miner <sup>21</sup> $a^{++}$ miner <sup>22</sup> , Heuristics miner <sup>21</sup>	+	$\begin{array}{c c} + & \#^+_{L_{2,s}}(a_1,b) \\ - & \#^{L_{2,s}}(a_1,b) \end{array}$	$\begin{array}{c c c c c c c c c c c c c c c c c c c $

ating more transitions then needed. On the other hand,  $l_3$  results in gain of precision, as  $\mathfrak{L}(N_3)$ , does not contain  $\langle a, b_1, e \rangle$  and  $\langle a, b_2, d \rangle$ , while  $N_1$  does not distinguish between  $b_1$  and  $b_2$ , which suggests that both types of traces are possible.

#### 4. Evaluation Method for Label Refinements for Process Models

In the previous section we showed that we can compare the usefulness of a label refinement by inspecting the Petri net obtained with process discovery. A naive way to evaluate label refinement would be to apply process discovery to all possible label refinements. The number of possible label refinements to consider can however be large and process discovery is a computationally expensive task. Therefore, this naive approach quickly becomes computationally infeasible. We now present a way to estimate the usefulness of a label refinement based on statistics and log relations.

Algorithm 1 shows the steps of the label refinements evaluation method. The evaluation method consists of an entropy-based component that measures whether a label refinement makes the log statistics more unbalanced, and a statistical test that tests whether there is a label statistic that tests whether the label refinement makes a statistically significant difference to at least one of the log statistics. In the following two sections we described the entropy-based measure and the statistical testing respectively.

#### 4.1. Log Statistics

Event ordering patterns are crucial to most process discovery algorithms. Table 2 provides an overview of wellknown log-based ordering relations described in process discovery literature <sup>17,18,22,21</sup> and provides examples. Let *L* be an event log. Let *b*,  $c \in A_L$ . Formal definitions of these log-based ordering statistics are as follows:

- #<sup>+</sup><sub>L,></sub>(b, c) is the number of occurrences of b in the traces of L that are directly followed by c, i.e. in some σ ∈ L, i ∈ {1,..., |σ|} we have [σ(i)]<sub>a</sub> = b and [σ(i + 1)]<sub>a</sub> = c (direct successor), #<sup>-</sup><sub>L,></sub>(b, c) is the number of occurrences of b which are not directly followed by c;
- $\#_{L,>>}^+(b,c)$  and  $\#_{L,>>}^-(b,c)$  is the number of occurrences of *b* that are, respectively, are not, followed by *c*: for a trace  $\sigma \in L$  and  $i \in \{1, ..., |\sigma|\}$ , and  $[\sigma(i)]_a = [\sigma(i+2)]_a = b$  and  $[\sigma(i+1)]_a = c$  and  $b \neq c$  (length-two loops);
- #<sup>+</sup><sub>L,>>></sub>(b, c) and #<sup>-</sup><sub>L,>>></sub>(b, c) is the number of occurrences of b that are, respectively are not, eventually followed by c: for a trace σ ∈ L, i, j ∈ N with i < j, [σ(i)]<sub>a</sub> = b and [σ(j)]<sub>a</sub> = c (direct or indirect successor).

In the general sense, let  $\#_{L,s}^+(b,c)$  and  $\#_{L,s}^-(b,c)$  be the count of the number of b's that <u>do</u>, respectively do not, satisfy relation s in log L with respect to c.

Let *L* be an event log. Let  $l_1$  and  $l_2$  be two relabeling functions that are to be compared, such that  $l_2 <= l_1$ . Let  $L_1 = l_1(L)$  and  $L_2 = l_2(L)$ . Let  $l_1$  and  $l_2$  have the property  $\{a_1, a_2 \in A_{L_2}\}|\exists_{\sigma_1,\sigma_2 \in L} : l_1(\sigma_1) = \lambda a \wedge l_1(\sigma_2) = \lambda' a \wedge l_2(\sigma_1) = \zeta a_1 \wedge l_2(\sigma_2) = \zeta' a_2\} \neq \emptyset$ , that is,  $l_2$  refines activity *a* into distinct activities  $a_1$  and  $a_2$ . The difference in control flow between  $a_1$  and  $a_2$  can be expressed as the dissimilarity in log-based ordering statistics between event label  $a_1$  and  $b \in A_{L_2} \setminus \{a_1, a_2\}$  on the one hand, and  $a_2$  and *b* on the other hand. Each log-based ordering statistics of  $a_1$  and  $a_2$  with regard to any other activity *b* can be formulated in the form of a contingency table, as shown in Table 3.

Directly follows			Directly precedes			es	Eventually follows				Eventually precedes				
	Tossing & turn- ing	Getting up	Bed- room motion		Tossing & turn- ing	Getting up	Bed- room motion		Tossing & turn- ing	Getting up	Bed- room motion		Tossing & turn- ing	Getting up	Bed- room motion
$\stackrel{+}{\stackrel{-}{\rightarrow}}$	0 16	0 5	0 21	$\stackrel{+}{\rightarrow}$ $\stackrel{-}{\rightarrow}$	0 16	5 0	5 16	$\xrightarrow{+}{\rightarrow}$ $\xrightarrow{-}{\rightarrow}$	0 16	0 5	0 21	$\stackrel{+}{\rightarrow}$ $\stackrel{-}{\rightarrow}$	16 0	5 0	21 0

Table 4: Contingency tables for comparing the behavior of the two refined labels

#### 4.2. Information Gain

The binary entropy function,  $H_b(p) = -p \log_2 p - (1-p) \log_2(1-p)$ , where  $0 \log_2 0 = 0$ , is a measure of uncertainty. Applied on a log statistic, the binary entropy function represents a degree of nondeterminism. Nondeterministic, unbalanced, log statistics are a helpful to process discovery algorithms that operate of log statistics, as it provides low uncertainty to the mining algorithm. Low entropy in the log statistics indicate high predictability of the process, making it easier for process discovery algorithms to return a sensible process model.

Consider the contingency tables in Table 4, based on log statistics obtained from Table 1 between the events labeled *Tossing & turning* and *Getting up* and the events labeled *Living room motion*. On the right hand side of the table, separated by the bar, are the log statistics of the before-split label in the before-split log. All five events with label *Getting up* directly precede an event with label *Living room motion*, while all sixteen events with label *Tossing & turning* are <u>not</u> directly preceded by *Living room motion*. Furthermore, all events with refined labels do <u>not</u> directly or eventually follow an event with label *Living room motion*, and all events with refined labels do eventually precede an event with label *Living room motion*.

Log statistics with a high degree of non-determinism, like the directly precedes statistic of the bedroom motion events before the split, might confuse a mining algorithm as there is no clear structure here: the *Bedroom motion* event might directly precede *Livingroom motion*, but most of the time it does not. After the split we see a completely deterministic directly precedes statistic, where *Tossing & turning* never and *Getting up* always directly precedes *Livingroom motion*. This increased determinism is reflected by the entropy of the directly precedes statistic before and after the split. Before the split we have  $-\frac{5}{5+16} \log_2 \frac{5}{5+16} - \frac{16}{5+16} \log_2 \frac{16}{5+16} = 0.7919$  bit of entropy in the directly precedes statistic, compared to  $-\frac{0}{0+16} \log_2 \frac{0}{0+16} - \frac{16}{0+16} \log_2 \frac{16}{0+16} = 0$  bit of entropy for *Tossing & turning* and  $-\frac{0}{0+5} \log_2 \frac{0}{0+5} - \frac{5}{0+5} \log_2 \frac{5}{0+5} = 0$  bit of entropy for *Getting up*. The conditional entropy of the log statistic after the split is the weighted average of the entropy of the labels created in the split, which is  $-\frac{16}{21}0 \times \frac{5}{21}0 = 0$ . The information gain of this label split with regard to the directly precedes *Livingroom motion* statistic is equal to the total entropy of the log statistic prior to the split, minus the conditional entropy after the split, this 0.7919 - 0 = 0.7919. Relative information gain<sup>6</sup> is a metric that provides insight in the ratio of bits of entropy reduced by a refinement, and can be calculated by dividing the information gain by the before-split entropy. The relative information gain of the directly precedes *Livingroom motion* statistic is  $\frac{0.7919}{0.7919} = 1$ . Figure 2 shows the effect of this label refinement on the resulting Petri net obtained by process discovery.

So far we have calculated the Relative information gain for a single log statistic. A label refinement however can have impact on multiple log statistics at once. We need a measure that integrates the information gain values of all log statistics to express the quality of a label refinement with respect to the determinism of the log statistics. We therefore sum over the entropy of all log statistics before the label split to obtain the total before-split entropy. We sum over the conditional entropies of all log statistics after the label split to obtain the total after-split entropy. Information Gain and Relative information gain are calculated as before. We let *relative\_information\_gain*( $L_1, L_2$ ) be the function that returns the Relative information gain based on the pre-split log  $L_1$  and post-split log  $L_2$ , where the set of refined label pairs in  $L_2$  from which the log statistics are used corresponds to  $\{a_1, a_2 \in A_{L_2} | \exists_{\sigma_1, \sigma_2 \in L} : l_1(\sigma_1) = \lambda a \land l_1(\sigma_2) = \lambda' a \land$ , with the *a* the corresponding label in  $L_1$ .

#### 4.3. Statistical Testing

Relative information gain can be high by chance for a refinement when the generated refined labels are infrequent. Statistical testing of log statistic differences in addition to calculating relative information gain enables us to distinguish

#### Algorithm 1 Algorithm of the label refinement statistical evaluation method

```
Input: Event log L, Relabeling functions l_1 and l_2 such that l_2 <= l_1,
Output: the Relative information gain of l_1 w.r.t l_2,
Parameters: Set of log-based ordering statistics S,
Significance level \alpha.
         all_significant_different = true; L_1=l_1(L); L_2=l_2(L);
          \texttt{split\_set} = \{a_1, a_2 \in A(L_2) | \exists_{\sigma_1, \sigma_2 \in L} : l_1(\sigma_1) = \lambda a \land l_1(\sigma_2) = \lambda' a \land l_2(\sigma_1) = \zeta a_1 \land l_2(\sigma_2) = \zeta' a_2\};
          For each a_1, a_2 \in \text{split_set}:
                 pair_significant_different = false;
                  For each \{b \in A(L_2) \setminus \{a_1, a_2\}\}:
                          For each s \in S:
                                  \mathbf{p} = fisher\_test(\#_{L_{2,s}}^{+}(a_{1}, b), \#_{L_{2,s}}^{-}(a_{1}, b), \#_{L_{2,s}}^{+}(a_{2}, b), \#_{L_{2,s}}^{-}(a_{2}, b));
                                  If (p < \alpha) pair_significant_different = true;
                  If (! pair_significant_different)
                          all_significant_different = false;
          If (all_significant_different)
                 return relative_information_gain(L1, L2);
          Else return 0.0:
```

between information gain obtained by chance and actual information gain. Fisher's exact test<sup>5</sup> is a statistical significance test for the analysis of contingency tables. When applied to the table above, it calculates a *p*-value for the null hypothesis that  $a_1$  and  $a_2$  events are equally likely to hold log relation s with regard to label b. Fisher's exact test assumes individual observations to be independent and row and column totals to be fixed. Independence of individual observations might be affected by the grouping of events in traces. In this paper we consider individual observations independence to be working assumption. The test was designed for experiments where both the row and column totals where conditioned. In our setting, the column totals are conditioned by the relabeling function, as the number of events of each label depends on the relabeling. The row totals however, are not conditioned and are an observation. Fisher's exact test is not strictly speaking exact when one or both of the row or column totals are unconditioned, but will instead be slightly conservative<sup>9</sup>, meaning that the probability of the p-value being less than or equal to the significance level when the null hypothesis is true is less than the significance level. Fisher's exact test is computationally expensive for large numbers of observations. For large sample sizes, either the  $\chi^2$  test of independence or the G-test of independence can be used, which are both found to be inaccurate for small sample sizes. A popular guideline is to not use the  $\chi^2$  test of independence or the G-test for samples sizes less than one thousand<sup>9</sup>. The computational complexity of the evaluation procedure is  $O(|S| \times |A(L)| \times |split_{set}|)$ . Many process discovery algorithms are exponential in the number of labels<sup>16</sup>. Based on this we can conclude that statistical evaluation of label refinements is computationally less expensive than checking label refinement usefulness through process discovery.

#### 4.4. Correcting for Multiple Testing

The computational complexity indicates the number of hypothesis tests performed. When a large set of potential label refinements is evaluated, the evaluation method described is susceptible to the repeated testing problem. The larger the set of hypotheses tested, the higher the probability of incorrectly rejecting the null hypothesis in at least one of the hypothesis tests. Applying a Bonferroni correction<sup>3,4</sup> to the hypothesis tests performed in the statistical evaluation method of label refinements keeps the familywise error rate constant.

#### 4.5. Example Case

Consider the event log in Table 1 and imagine a scenario where a home care worker knows from experience that the elderly always sets his alarm clock at 8:30 AM. Based on such expert knowledge we are able to define a label refinement such that all bedroom movements after 8:30 AM are considered as *Getting up* events, while all other bedroom movements are considered to be *Tossing & turning* events. The rightmost column shows the refined labels obtained through this expert relabeling function. To evaluate the usefulness of this label refinement from a process model point of view, we apply the statistical evaluation method described in Section 4. As parameters we set the significance level threshold to the frequently used value of 0.01.

I refinenferroni Table 5: Results of the statistical tests for the evaluation of label refinement usefulness

Log statistic	P-value
Directly follows Directly precedes Eventually follows Eventually precedes	$ \begin{array}{c c} 1 \\ 4.91 \times 10^{-5} \\ 1 \\ 1 \end{array} $

### Table 5 shows the outcome of the statistical tests performed as part of the label refinement usefulness evaluation. Four hypothesis tests have been performed, after Bonferroni correction each hypothesis test is tested at significance level $\frac{0.01}{4} = 0.0025$ . The direct following statistic of *Tossing & turning* and *Getting up* with *Living room motion* is statistically significantly given this significance level. The label refinement constructed with expert knowledge is found to be a useful label refinement through statistical evaluation.

## 5. Real life evaluation

We apply our label refinement evaluation method to a set of candidate label refinements on the Van Kasteren smart home environment data set<sup>19</sup> in order to illustrate the effects of label splits in the context of process mining of real life processes. The van Kasteren data set consists of 1285 events divided over fourteen different sensors. Events are segmented in days from midnight to midnight, to define cases in the event log. The candidate set of label refinements consists of splitting each of the fourteen event types *t* into two event types based on the their time in the day, such that *t* events where the time since the start of the day is smaller than the median for *t* are separated from *t* events where it is equal to or larger than the median. Figure 5 shows the *dependency graph* obtained with the Heuristics Miner<sup>21</sup>. A *dependency graph* depicts causal relations between activities that meet a certainty threshold. A *dependency graph* can be directly converted into a Petri net<sup>21</sup>, however, for the sake of readability we included the *dependency graphs* instead of the Petri nets. The precision<sup>10</sup> of the Petri net corresponding to Figure 5 is 0.56 on a scale from 0 to 1.

Out of the fourteen candidate label refinements, two label refinements are selected by our approach. The first label refinement found is the split of *Hall-bathroom door* into *Hall-bathroom door\_1* and *Hall-bathroom door\_2*, with a timestamp below, respectively above or equal to the median time in the day of *Hall-bathroom door* events. The resulting labels of this refinement are statistically significantly different in terms of their eventually follows relation with *Front door* (p-value:  $3.06 \times 10^{-26}$ ) and their eventually follows relation with *Plates cupboard* (p-value:  $3.66 \times 10^{-23}$ ) and Microwave  $1.85 \times 10^{24}$ . The relative information gain on the whole event log caused by this label refinement is 3.47%. Figure 6 shows a Heuristics Net mined with the Heuristics Miner<sup>21</sup> on the van Kasteren log with the refined *Hall-bathroom door* label. The model discovered on the log with this label refinement (Figure 6) has a precision of 0.69, up from 0.53 without the refinement. The increased precision shows that the label refinement helps restricting the share of behavior allowed



Fig. 5: Heuristics net showing original van Kasteren data set



Fig. 6: Heuristics net showing the label refinement on hall-bathroom door on the van Kasteren data set



Fig. 7: Heuristics net showing the label refinement on cups cupboard on the van Kasteren data set

by the model that is not covered by the event log. The second label refinement found is the split of *Cups cupboard* into *Cups cupboard\_1* and *Cups cupboard\_2*. The resulting labels of this refinement are statistically significantly different in terms of their eventually precedes relation with *Groceries cupboard* (p-value:  $2.53 \times 10^{-34}$ ) and their eventually follows relation with *Fridge* (p-value:  $2.2 \times 10^{-22}$ ). The relative information gain on the whole event log caused by this label refinement is 0.53%. Figure 7 shows a Heuristics Net mined with the Heuristics Miner on the van Kasteren log with the refined *Cups cupboard* label, of which the precision is 0.61, up to 0.53 without the refinement. The label refinement with higher information gain also results in a higher improvement in terms of precision, which is in agreement with the intuition that more deterministic log statistics help the miner in mining structured, non-flower-like, models.

#### 6. Conclusion & Future Work

We have provided a theoretical and conceptual notion of when label refinements and abstractions are useful from a process discovery point of view. Based on this notion of usefulness, we have shown a framework based on statistics and information theory to evaluate the usefulness of a label refinement or abstraction. In addition, we have shown the applicability of this statistical framework through a real life smart home case, where our method selected two label refinements out of a larger candidate set that increased the precision of the resulting process model. Methods for automatic inference of useful label refinements from event attributes are still to be explored. Such methods may generate a set of candidate label refinements, after which the statistical evaluation method described in this paper can be used to select the most promising label refinement from a set of candidate label refinements.

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